## Automatic Control

## Chapter three

Signal flow graph

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## Block diagrams and SFG

## Signal Flow Graph (SFG)

A signal-flow graph (SFG) may be regarded as a simplified version of a block diagram

## Basic Elements of an SFG

Node: represent variables
Arrow head: the direction of the signal flow
Line: where the signal flow
Transfer function (a): the relation between the variables
Variables (y)


Mathematical relation

$$
y_{2}=a_{12} y_{1}
$$

## Block diagrams and SFG

## Signal Flow Graph (SFG)

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Example 3-2-1 Golnaraghi (2010
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Draw the SFG for the following system of linear algebraic equations

$$
\begin{aligned}
& y_{2}=a_{12} y_{1}+a_{32} y_{3} \\
& y_{3}=a_{23} y_{2}+a_{43} y_{4} \\
& y_{4}=a_{24} y_{2}+a_{34} y_{3}+a_{44} y_{4} \\
& y_{5}=a_{25} y_{2}+a_{45} y_{4}
\end{aligned}
$$

## Block diagrams and SFG

## Example 3-2-1 Golnaraghi (2010

## Solution



O
$\mathrm{Y}_{4}$
$\stackrel{\circ}{y_{5}}$
(a) $y_{2}=a_{12} y_{1}+a_{32} y_{3}$

(b) $y_{2}=a_{12} y_{1}+a_{32} y_{3} \quad y_{3}=a_{23} y_{2}+a_{43} y_{4}$


## Block diagrams and SFG

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## Solution


(d) Complete signal-flow graph

## Block diagrams and SFG

## Basic Properties of SFG

$>$ SFG applies only to linear systems.
$>$ The equations for which an SFG is drawn must be algebraic equations in the form of cause-and-effect.
$>$ Nodes are used to represent variables. Normally, the nodes are arranged from left to right, from the input to the output, following a succession of cause-and-effect relations through the system.
-Signals travel along branches only in the direction described by the arrows of the branches.
$>$ The branch directing from node $y_{k}$ to $y_{j}$ represents the dependence of $y_{k}$ upon $y_{j}$ but not the reverse.
$>A$ signal $y_{k}$ traveling along a branch between $y_{k}$ to $y_{j}$ is multiplied by the gain of the branch $a_{k j}$ so a signal $a_{k j} y_{k}$ is delivered at $y_{j}$

## Block diagrams and SFG

## Definitions of SFG Terms

$>$ Input Node (Source): An input node is a node that has only outgoing branches
$>$ Output Node (Sink): An output node is a node that has only incoming branches
$\rightarrow$ Path: A path is any collection of a continuous succession of branches traversed in the same direction.
>Forward Path: A forward path is a path that starts at an input node and ends at an output node and along which no node is traversed more than once
>Path Gain: The product of the branch gains encountered in traversing a path is called the path gain
-Loop: A loop is a path that originates and terminates on the same node and along which no other node is encountered more than once.
$>$ Forward-Path Gain: The forward-path gain is the path gain of a forward path.
$>$ Loop Gain: The loop gain is the path gain of a loop.
$>$ Nontouching Loops: Two parts of an SFG are nontouching if they do not share a common node.

## Block diagrams and SFG

## SFG Algebra

$\Rightarrow$ The value of the variable represented by a node is equal to the sum of all the signals entering the node.
$>$ The value of the variable represented by a node is transmitted through all branches leaving the node


$$
\begin{aligned}
& y_{1}=a_{21} y_{2}+a_{31} y_{3}+a_{41} y_{4}+a_{51} y_{5} \\
& y_{6}=a_{16} y_{1} \\
& y_{7}=a_{17} y_{1} \\
& y_{8}=a_{18} y_{1}
\end{aligned}
$$

## Block diagrams and SFG

## SFG Algebra

$>$ Parallel branches in the same direction connecting two nodes can be replaced by a single branch with gain equal to the sum of the gains of the parallel branches

$>$ A series connection of unidirectional branches can be replaced by a single branch with gain equal to the product of the branch gains.



## Block diagrams and SFG

Relation between SFG and block diagram

## Example


(a)


## Block diagrams and SFG

## Gain Formula for SFG

To find the relation between the SFG input and output, we can use the gain formula for SFG:

$$
M=\frac{y_{\text {out }}}{y_{\text {in }}}=\sum_{k=1}^{N} \frac{M_{k} \Delta_{k}}{\Delta}
$$

where
$y_{\text {in }}=$ input-node variable
$y_{\text {out }}=$ output-node variable
$M=$ gain between yin and $y_{\text {out }}$
$N=$ total number of forward paths between $y_{\text {in }}$ and $y_{\text {out }}$
$M_{k}=$ gain of the $k t h$ forward paths between $y_{\text {in }}$ and $y_{\text {out }}$
$\Delta=1-\sum_{i} L_{i 1}+\sum_{j} L_{j 2}-\sum_{k} L_{k 3}+\ldots$
$\Delta=1$ - (sum of the gains of all individual loops) + (sum of products of gains of all possible combinations of two nontouching loops) - (sum of products of gains of all possible combinations of three nontouching loops) +...
$\Delta \mathrm{k}$ is the $\Delta$ for that part of the SFG that is nontouching with the kth forward path.

## Block diagrams and SFG

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$\Delta \mathrm{k}$ is the $\Delta$ for that part of the SFG that is nontouching with the kth forward path.

## Block diagrams and SFG

## Example 3-2-3 Golnaraghi (2010

determine the gain between $\mathrm{y}_{1}$ and $\mathrm{y}_{5}$ using the gain formula for the following SFG.


## Block diagrams and SFG

## Example 3-2-3 GoInaraghi (2010

## Solution



The three forward paths between $y_{1}$ and $y_{5}$ and the forward-path gains are

$$
\begin{array}{lll}
M_{1}=a_{12} a_{23} a_{34} a_{45} & \text { Forward path: } & y_{1}-y_{2}-y_{3}-y_{4}-y_{5} \\
M_{2}=a_{12} a_{25} & \text { Forward path: } & y_{1}-y_{2}-y_{5} \\
M_{3}=a_{12} a_{24} a_{45} & \text { Forward path: } & y_{1}-y_{2}-y_{4}-y_{5}
\end{array}
$$

## Block diagrams and SFG

## Example 3-2-3 GoInaraghi (2010

## Solution

There is only one pair of nontouching loops; that is, the two loops are:

The four loops of the SFG

$$
y_{2}-y_{3}-y_{2} \text { and } y_{4}-y_{4} .
$$

Thus, the product of the gains of the two nontouching loops is

$$
L_{12}=a_{23} a_{32} a_{44} .
$$

$$
L_{41}=a_{44}
$$


$L_{31}=a_{24} a_{43} a_{32}$


## Block diagrams and SFG

## Example 3-2-3 GoInaraghi (2010

## Solution

All the loops are in touch with forward paths $M_{1}$ and $M_{3}$. Thus, $\Delta_{1}=\Delta_{3}=1$. Two of the loops are not in touch with forward path $M_{2}$. These loops are $y_{3}-y_{4}-y_{3}$ and $y_{4}-y_{4}$.Thus

$$
\Delta_{2}=1-a_{34} a_{43}-a_{44} .
$$

Substitute in gain formula

$$
\begin{aligned}
& M=\frac{y_{5}}{y_{1}}=\frac{M_{1} \Delta_{1}+M_{2} \Delta_{2}+M_{3} \Delta_{3}}{\Delta} \\
& M=\frac{\left(a_{12} a_{23} a_{34} a_{45}\right)+\left(a_{12} a_{25}\right)\left(1-a_{34} a_{43}-a_{44}\right)+a_{12} a_{24} a_{45}}{1-\left(a_{23} a_{32}+a_{34} a_{43}+a_{24} a_{32} a_{43}+a_{44}\right)+a_{23} a_{32} a_{44}}
\end{aligned}
$$

